

Scaling limit of half-space last-passage percolation models

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Scaling limit in full-space

Exact-solvable model

(Rost, 81') $(4n)^{-1}T_{(1,1),(n,n)} \rightarrow 1$ in probability

(Johannson, 00') Using RSK correspondence, i.e., LPP realization \rightarrow pair of Young tableaux

$$\mathbb{P}(T_{(1,1),(n,n)} < t) = \frac{1}{Z} \int_{[0,t]^n} \prod_{1 \leq i < j \leq n} (x_i - x_j)^2 \prod_{1 \leq i \leq n} e^{-x_i} dx_i$$

Then (using Fredholm determinant)

$$\mathbb{P}(T_{(1,1),(n,n)} < 4n + x2^{4/3}n^{1/3}) \rightarrow F_{GUE}(x)$$

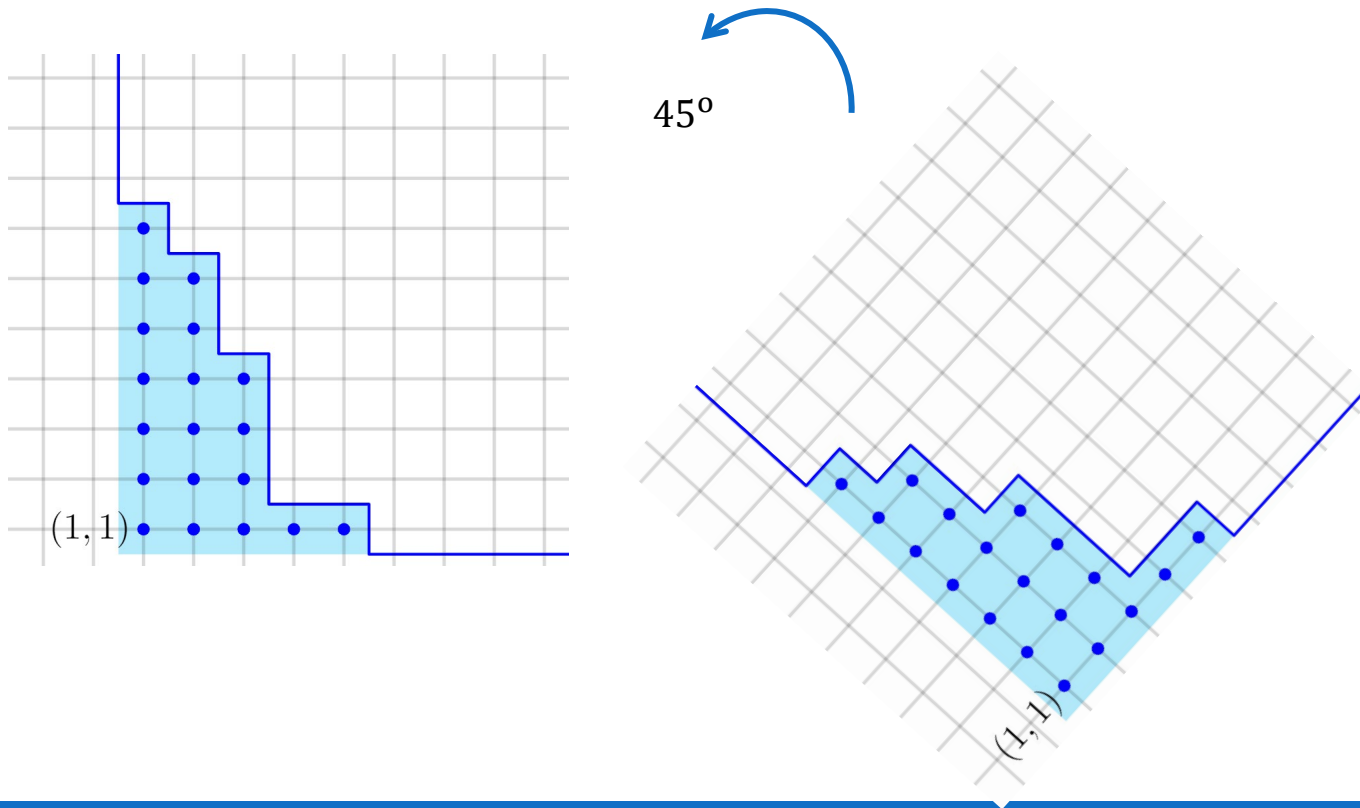
i.e., $T_{(1,1),(n,n)} \approx 4n + 2^{4/3}n^{1/3}X$, with $X \sim GUE$ Tracy-Widom

(Borodin-Ferrari, 08') $2^{-4/3}n^{-1/3} \left(T_{(1,1),(n+x(2n)^{2/3}, n-x(2n)^{2/3})} - 4n \right) \rightarrow \mathcal{A}(x)$

\mathcal{A} : Airy process; $\mathcal{A}(x) + x^2$ is stationary

As a growth process

Metric ball $B_t = \{v \in \mathbb{N}^2 : T_{(1,1),v} < t\}$



Height function $H_t: \mathbb{Z} \rightarrow \mathbb{Z}$,
with $H_t(x+1) = H_t(x) \pm 1$,

- Markov process : flip with rate 1 independently
- Metric ball B_t : initial condition $H_0(x) = |x|$
- Can also take more general initial H_0

Scaling limit as a Markov process?

KPZ fixed point (full-space)

Height function process $(H_t)_{t \geq 0}$, starting from general H_0

For a family $(H_t^{(\varepsilon)})_{t \geq 0}$, scaling: $h_t^\varepsilon(x) = -\varepsilon^{1/2} \left(H_{2\varepsilon^{-3/2}t}^{(\varepsilon)}(2\varepsilon^{-1}x) - \varepsilon^{-3/2}t \right)$

(Matetski-Quastel-Remenik, 16')

As $\varepsilon \rightarrow 0$, assume that h_0^ε converges to $f: \mathbb{R} \rightarrow \mathbb{R} \cup \{-\infty\}$. Then for $t > 0$, h_t^ε converges as $\varepsilon \rightarrow 0$, to $\mathfrak{h}_t f$, the **KPZ fixed point** starting from f at time t .

KPZ fixed point is a *Markov process on (upper semi-continuous) functions* $\mathbb{R} \rightarrow \mathbb{R} \cup \{-\infty\}$.

Exact formulas For upper semi-continuous $f: \mathbb{R} \rightarrow \mathbb{R} \cup \{-\infty\}$

and lower semi-continuous $g: \mathbb{R} \rightarrow \mathbb{R} \cup \{\infty\}$, there is

$$\mathbb{P}(\mathfrak{h}_t f < g) = \det \left(\mathbf{I} - \mathbf{K}_{t/2}^{\text{hypo}(f)} \mathbf{K}_{-t/2}^{\text{epi}(g)} \right)_{L^2(\mathbb{R})}$$

In particular, $\mathfrak{h}_1 \delta_0 = \mathcal{A}$.

Here $\delta_0(0) = 0$, $\delta_0(x) = -\infty$ for any $x \neq 0$.

Directed landscape (full-space)

(Dauvergne-Ortmann-Virag, 18', Dauvergne-Virag, 21') 2D 1:2:3 scaling limit

As $n \rightarrow \infty$

$(x, s; y, t) \mapsto 2^{-4/3} n^{-1/3} (T_{R_n(x,s), R_n(y,t)} - 4n(t-s) - 2^{8/3} n^{2/3} (y-x))$ converges

where $R_n(x, s) = (ns + 2^{5/3} n^{2/3} x, ns)$

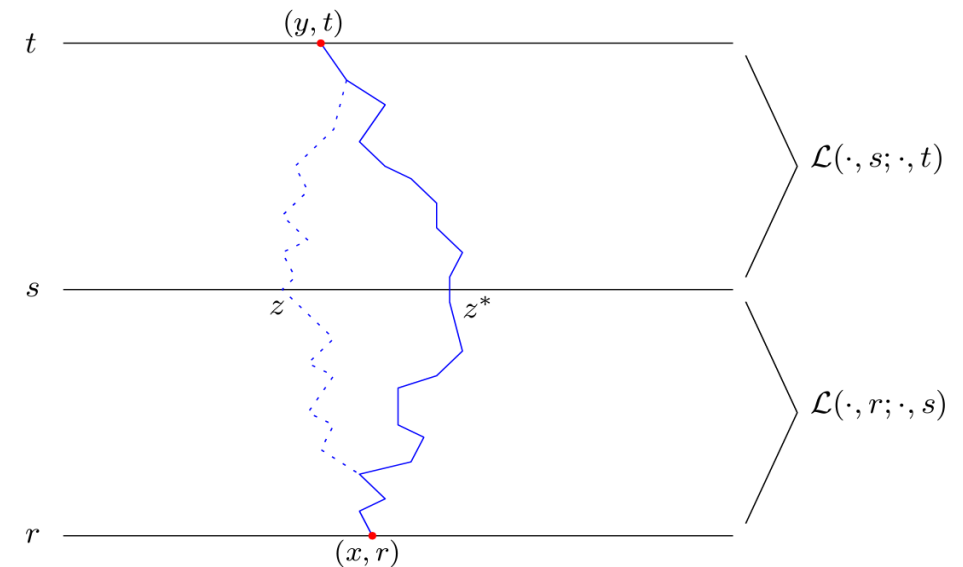
The limit a four-parameter random function

$\mathcal{L}: \mathbb{R}_{\uparrow}^4 \rightarrow \mathbb{R}$, where $\mathbb{R}_{\uparrow}^4 = \{(x, s; y, t) \in \mathbb{R}^4: s < t\}$

(the **directed landscape**)

Composition law $\mathcal{L}(x, r; y, t) = \max_z \mathcal{L}(x, r; z, s) + \mathcal{L}(z, s; y, t)$

This gives a *directed metric* on \mathbb{R}^2



Random metric generates growth process

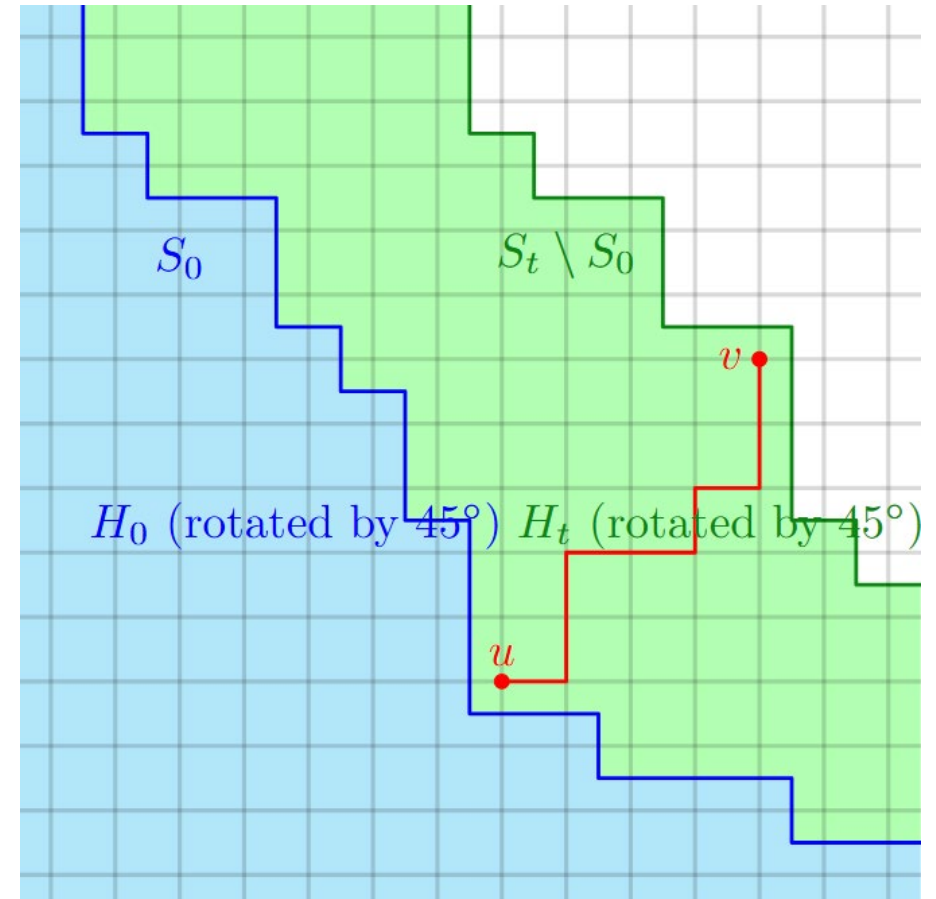
Growth process $(H_t)_{t \geq 0}$ starting from general H_0 : take S_0 according to H_0 ; define

$$S_t = \{v \in \mathbb{Z}^2 : \max_{u \notin S_0} T_{u,v} < t\}$$

Therefore, we have **variational formula**:

$$\mathfrak{h}_t f(y) = \max_x f(x) + \mathcal{L}(x, 0; y, t)$$

i.e., directed landscape generates KPZ fixed point.



Scaling limit in half-space

Recall setup:

- $\xi(i, j) = \xi(j, i) \sim \text{Exp}(1)$, for $i > j \in \mathbb{Z}$
- $\xi(i, i) \sim \text{Exp}(a)$, for $i \in \mathbb{Z}$

(Baik-Barraquand-Corwin-Suidan, 16') For fixed a :

$$\mathbb{P}\left(T_{(1,1),(n,n)}^a < 4n + x2^{4/3}n^{1/3}\right) \rightarrow F_{GSE}(x), \quad \text{if } a > 1/2,$$

$$\mathbb{P}\left(T_{(1,1),(n,n)}^a < 4n + x2^{4/3}n^{1/3}\right) \rightarrow F_{GOE}(x), \quad \text{if } a = 1/2,$$

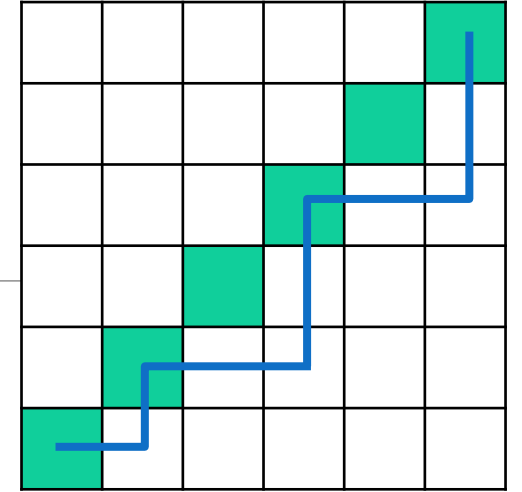
$$\mathbb{P}\left(T_{(1,1),(n,n)}^a < na^{-1}(1-a)^{-1} + x\sigma_a n^{1/2}\right) \rightarrow G(x), \quad \text{if } a < 1/2, \quad (\text{Gaussian})$$

Scale a around $1/2$: take $a = (1 - 2^{-1/3}\theta n^{-1/3})/2$, for some $\theta \in \mathbb{R}$:

$$\mathbb{P}\left(T_{(1,1),(n,n)}^a < 4n + x2^{4/3}n^{1/3}\right) \rightarrow F_{cross,\theta}(x), \quad \text{formula given by Fredholm Pfaffian}$$

Also have convergence of the process $2^{-4/3}n^{-1/3} \left(T_{(1,1),(n+x(2n)^{2/3}, n-x(2n)^{2/3})}^a\right)$, $x \geq 0$.

Prediction goes back to Kardar, 85'. See also Baik-Rains, 99', Sasamoto-Imamura, 03', in different settings.



Half-space KPZ fixed point

Height function $H_t: \mathbb{Z}_{\geq 0} \rightarrow \mathbb{Z}$, with $H_t(x+1) = H_t(x) \pm 1$,

➤ Markov process : flip with rate 1 independently, except for rate a at 0.

For $(H_t^{(\varepsilon)})_{t \geq 0}$, scaling: $h_t^\varepsilon(x) = -\varepsilon^{1/2} \left(H_{2\varepsilon^{-3/2}t}^{(\varepsilon)}(2\varepsilon^{-1}x) - \varepsilon^{-3/2}t \right)$

Take either

- $a = (1 - \theta\varepsilon^{1/2})/2$, or
- $a > 1/2$, fixed. (Let $\theta = -\infty$ in this case.)

(X. Zhang, 24') As $\varepsilon \rightarrow 0$, assume that h_0^ε converges to $f: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R} \cup \{-\infty\}$.

Then for $t > 0$, h_t^ε converges (in finite dim distribution) as $\varepsilon \rightarrow 0$, to $\mathfrak{h}_t^\theta f$, the **half-space KPZ fixed point** starting from f at time t .

Again, given by exact formulas (Fredholm Pfaffian).

Half-space directed landscape

(Dauvergne-Z., 26)

As $n \rightarrow \infty$

$(x, s; y, t) \mapsto 2^{-4/3} n^{-1/3} \left(T_{R_n(x,s), R_n(y,t)}^a - 4n(t-s) - 2^{8/3} n^{2/3} (y-x) \right)$ converges,

where $R_n(x, s) = (ns + 2^{5/3} n^{2/3} x, ns)$

The limit a four-parameter random function

$$\mathcal{L}^\theta: \mathbb{R}_{+, \uparrow}^4 \rightarrow \mathbb{R}, \text{ where } \mathbb{R}_{+, \uparrow}^4 = \{(x, s; y, t) \in \mathbb{R}^4: x, y \geq 0; s < t\}$$

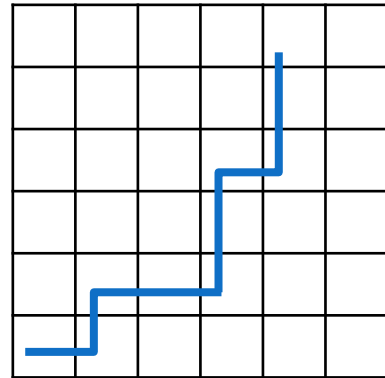
(the **half-space directed landscape with parameter** $\theta \in \mathbb{R} \cup \{-\infty\}$)

Composition law $\mathcal{L}^\theta(x, r; y, t) = \max_{z \geq 0} \mathcal{L}^\theta(x, r; z, s) + \mathcal{L}^\theta(z, s; y, t)$

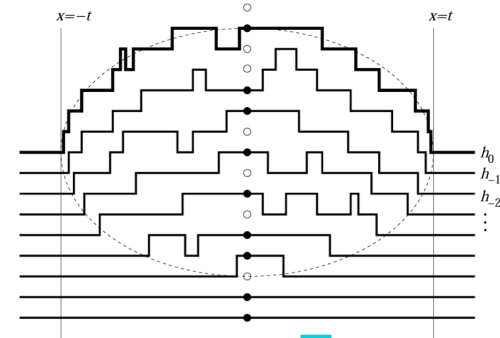
Variational formula $\mathfrak{h}_t^\theta f(y) = \max_{x \geq 0} f(x) + \mathcal{L}^\theta(x, 0; y, t)$

Previous route to landscape

In full-space, consider line ensembles



RSK correspondence



Some Gibbsian line ensemble (i.e., non-intersecting random walks)

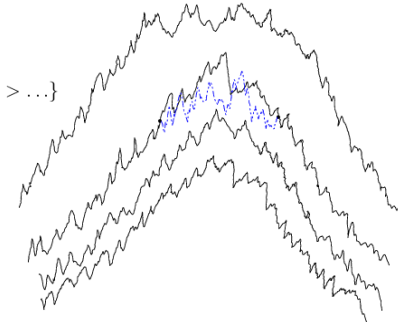


convergence to

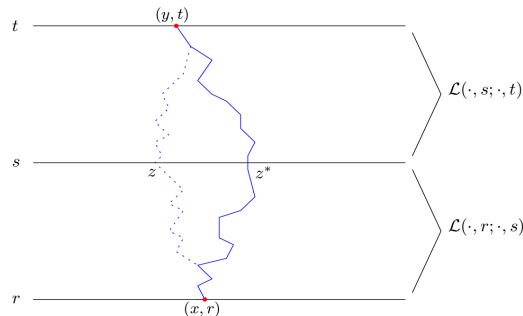
parabolic Airy line ensemble $\tilde{\mathcal{A}}$

$$\mathcal{A} = \{\mathcal{A}_1 > \mathcal{A}_2 > \dots\}$$

$$\mathcal{A}_1 = \text{Airy}_2$$



Prähofer-Spohn, 02'
Corwin-Hammond, 09';
characterization by
Aggarwal-Huang, 23'



Construct landscape
(Dauvergne-Ortmann-Virag, 18', Dauvergne-Virag, 21', Virag-Wu, 25')



Concurrent works in progress to get half-space directed landscape via line ensembles.

Alternative route

Characterize directed landscape from KPZ fixed point:

(Dauvergne, Z., 24') For random function $\mathcal{M}: \{(x, s; y, t): s < t\} \rightarrow \mathbb{R}$ that is continuous, consider the following conditions:

1. For any $s < t$ and $f: \mathbb{R} \rightarrow \mathbb{R} \cup \{-\infty\}$, supported on finitely many points, we have (in law)

$$\sup_x \mathcal{M}(x, s; \cdot, t) + f(x) = \mathfrak{h}_{t-s} f,$$

2. For any $r < s < t$, and x, y, z , we have $\mathcal{M}(x, r; y, t) \geq \mathcal{M}(x, r; z, s) + \mathcal{M}(z, s; y, t)$,

3. For any disjoint intervals $\{(s_i, t_i)\}_{i=1}^k$, $\mathcal{M}(\cdot, s_i; \cdot, t_i)$ are independent.

4. For the stationary horizon $\{\mathcal{H}_i\}_{i=1}^k$, we have $\left\{ \sup_x \mathcal{M}(x, s; \cdot, t) + \mathcal{H}_i(x) - C_i \right\}_{i=1}^k = \{\mathcal{H}_i\}_{i=1}^k$ in law.

If \mathcal{M} satisfies 1, 2, 3, and \mathcal{M}' satisfies 1, 2, 3, 4, then they are equal in law.

Corollary Exponential LPP converges under 1:2:3 scaling.

Proof Tightness follows from KPZ fixed point convergence; any subsequential limit satisfies 1, 2, 3, 4.

Corollary Any \mathcal{M} satisfies 1, 2, 3 must have the same law as the directed landscape \mathcal{L} .

Stationary horizon (full-space)

Brownian motion is *stationary* to the directed landscape:

for $B: \mathbb{R} \rightarrow \mathbb{R}$ being a two-sided Brownian motion with slope λ ,

$\sup_x \mathcal{L}(x, 0; \cdot, t) + B(x) - C$ is a Brownian motion with slope λ , where $C = \sup_x \mathcal{L}(x, 0; 0, t) + B(x)$.

➤ How about multiple slopes?

Given any $\lambda_1 > \dots > \lambda_k$, there should be a family of processes $\{\mathcal{H}_i\}_{i=1}^k$, where each \mathcal{H}_i is a two-sided Brownian motion with slope λ_i . Also, they are jointly stationary:

$$\left\{ \sup_x \mathcal{L}(x, s; \cdot, t) + \mathcal{H}_i(x) - C_i \right\}_{i=1}^k = \{\mathcal{H}_i\}_{i=1}^k$$

Busani, Seppäläinen, Sorensen, 2021-2022

Such $\{\mathcal{H}_i\}_{i=1}^k$ can be defined as follows:

➤ Consider two sided Brownian motions B_1, \dots, B_k , with drifts $\lambda_1 > \dots > \lambda_k$.

➤ Let $\mathcal{H}_i(x) - \mathcal{H}_i(y) = \lim_{z \rightarrow -\infty} B[(z, i) \rightarrow (x, k)] - B[(z, i) \rightarrow (y, k)]$

Here $B[u \rightarrow v]$ is the Brownian LPP passage time across B_1, \dots, B_k .

Half-space characterization

(Dauvergne, Z., 26) Fix $\theta \in \mathbb{R} \cup \{-\infty\}$. For random function $\mathcal{M}: \{(x, s; y, t): x, y \geq 0; s < t\} \rightarrow \mathbb{R}$ that is continuous, consider the following conditions:

1. For any $s < t$ and $f: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R} \cup \{-\infty\}$, supported on finitely many points, we have (in law)

$$\sup_{x \geq 0} \mathcal{M}(x, s; \cdot, t) + f(x) = \mathfrak{h}_{t-s}^\theta f,$$

2. For any $r < s < t$, and $x, y, z \geq 0$, we have $\mathcal{M}(x, r; y, t) \geq \mathcal{M}(x, r; z, s) + \mathcal{M}(z, s; y, t)$,

3. For any disjoint intervals $\{(s_i, t_i)\}_{i=1}^k$, $\mathcal{M}(\cdot, s_i; \cdot, t_i)$ are independent.

4. For the half-space stationary horizon $\{\mathcal{H}_i^\theta\}_{i=1}^k$, we have $\left\{ \sup_{x \geq 0} \mathcal{M}(x, s; \cdot, t) + \mathcal{H}_i^\theta(x) - C_i \right\}_{i=1}^k =$

$\{\mathcal{H}_i^\theta\}_{i=1}^k$ in law.

If \mathcal{M} satisfies 1, 2, 3, and \mathcal{M}' satisfies 1, 2, 3, 4, then they are equal in law.

Corollary Half-space Exponential LPP converges under 1:2:3 scaling. (Using half-space KPZ fixed point convergence.)

Corollary Any \mathcal{M} satisfies 1, 2, 3 must have the same law as the half-space directed landscape \mathcal{L}^θ .

Half-space stationary horizon

More complicated stationary processes (*Corwin-Barraquand, 18'*, in LPP and polymer settings.)

- when $\theta \leq 0$, there is one with slope λ , for each $\lambda \in \mathbb{R}_{\geq 0}$;
- when $\theta > 0$, there is one with slope λ , for each $\lambda \in \{-2\theta\} \cup (2\theta, \infty)$;
- in either case, it is a Brownian motion when $\lambda = -2\theta$.

		$Exp(\lambda_1/2 - \theta)$	\widetilde{B}_1

$Exp(\lambda_k/2 - \theta)$...	$Exp(\lambda_1/2 + \lambda_k/2)$	\widetilde{B}_k
0	...	$Exp(\lambda_1/2 - \lambda_k/2)$	B_k

		0	B_1

Dauvergne-Z., 25+

➤ Take Brownian motions $B_1, \dots, B_k, \widetilde{B}_k, \dots, \widetilde{B}_1$, with slopes $\lambda_1 > \dots > \lambda_k \geq 0 \geq -\lambda_k > \dots > -\lambda_1$. Also, $\lambda_k \geq \theta$.

➤ Let $\mathcal{H}_i^\theta(x) = TB[(k+1-i, i) \rightarrow (x, 2k)]$;

Here $TB[u \rightarrow v]$ denotes Exponential LPP followed by Brownian LPP

➤ Joint stationary

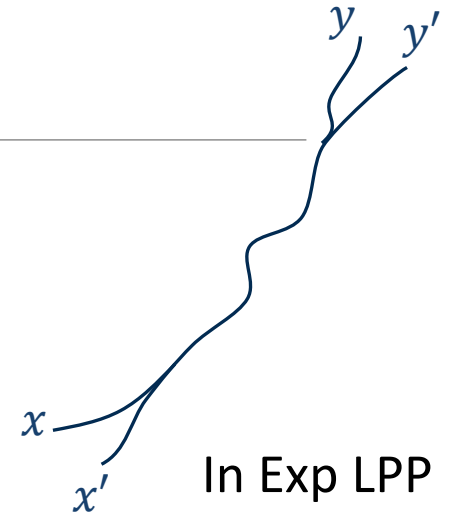
$$\left\{ \sup_x \mathcal{L}^\theta(x, s; \cdot, t) + \mathcal{H}_i^\theta(x) - C_i \right\}_{i=1}^k = \{\mathcal{H}_i^\theta\}_{i=1}^k$$

Proof ideas & ingredients

Heuristics (of why such characterizations hold?)
Geodesics coalesce.

For $|x - x'|$ and $|y - y'|$ small, likely

$$\mathcal{M}(x, 0; y, 1) + \mathcal{M}(x', 0; y', 1) = \mathcal{M}(x, 0; y', 1) + \mathcal{M}(x', 0; y, 1)$$

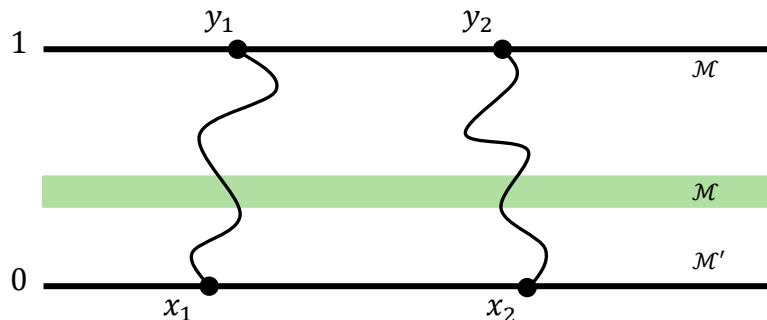


In Exp LPP

Proof of characterization to show in law $(\mathcal{M}(x_1, 0; y_1, 1), \mathcal{M}(x_2, 0; y_2, 1)) = (\mathcal{M}'(x_1, 0; y_1, 1), \mathcal{M}'(x_2, 0; y_2, 1))$

Use a *Lindeberg exchange strategy*, plus careful quantitative analysis, to exploit **coalescence**

(Originated in Lindeberg's proof of CLT, 1922; used in e.g., hydrodynamics *Bohadoran-Guiol-Ravishankar-Saada, 02'*; spin glass *Chatterjee, 04'*; random matrices: *Chatterjee, 05'*, *Tao-Vu, 07'*, *Knowles-Yin, 17'*; (2+1)D growth, *Caravenna-Sun-Zygouras, 21'*, *Tsai, 24'*)



Equal with high probability
(under a certain coupling)

